

HONEYBEE ROBOTICS
A BLUE ORIGIN COMPANY



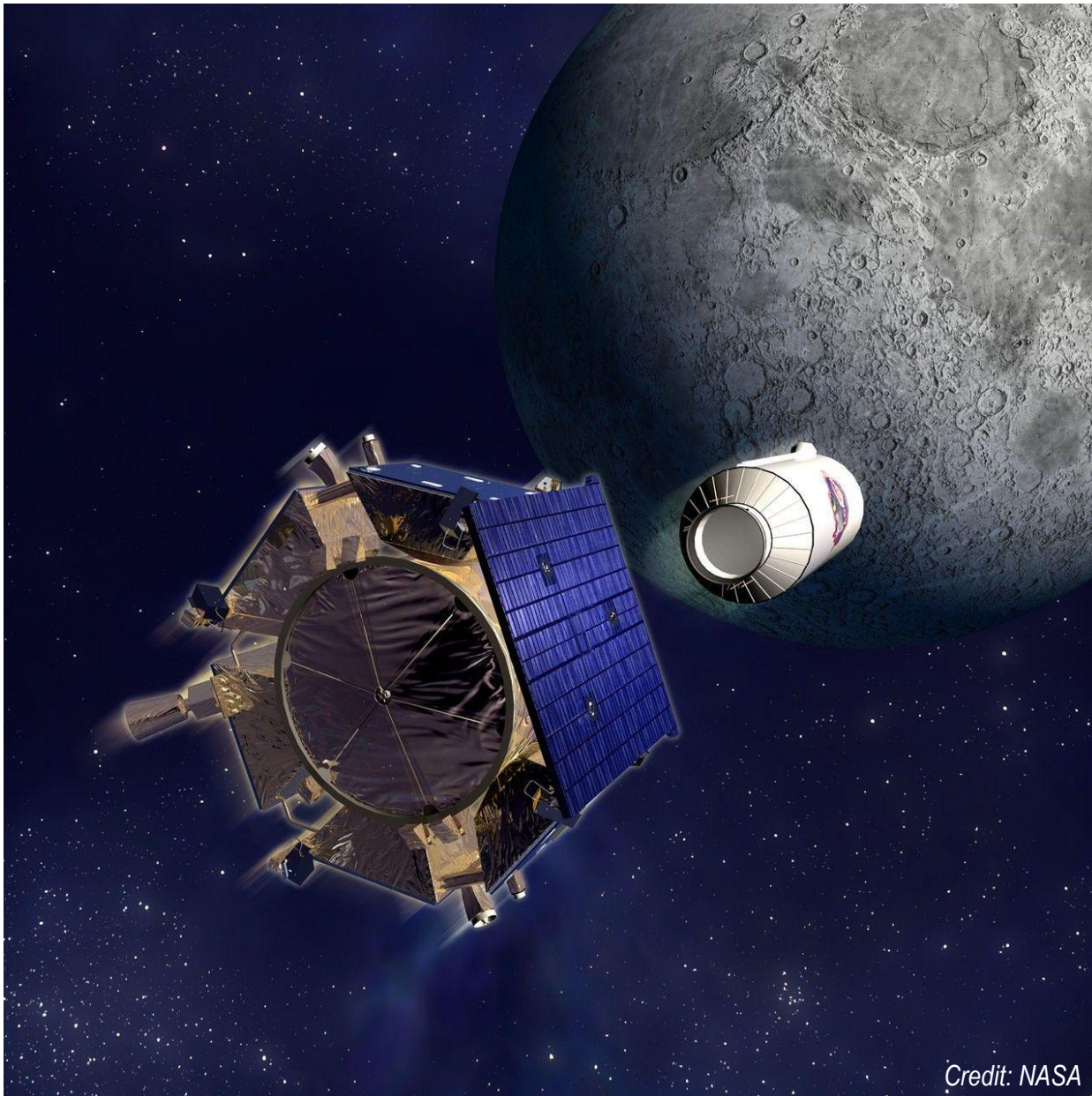
Results from End-to-End Testing with PVEx and the Lunar Capillary Absorption Spectrometer (LuCAS)

Isabel King, Sr. Research Engineer
6/2/2026

Lunar Volatiles



HONEYBEE ROBOTICS
A BLUE ORIGIN COMPANY



Credit: NASA

Table 2. Abundances derived from spectral fits shown in Fig. 3. The uncertainty in each derived abundance is shown in parenthesis [e.g., for H₂O: 5.1(1.4)E19 = $5.1 \pm 1.4 \times 10^{19} \text{ cm}^{-2}$] and was derived from the residual error in the fit and the uncertainty in the radiance at the appropriate band center.

Compound	Molecules cm ⁻²	% Relative to H ₂ O(g)*
H ₂ O	5.1(1.4)E19	100.00%
H ₂ S	8.5(0.9)E18	16.75%
NH ₃	3.1(1.5)E18	6.03%
SO ₂	1.6(0.4)E18	3.19%
C ₂ H ₄	1.6(1.7)E18	3.12%
CO ₂	1.1(1.0)E18	2.17%
CH ₃ OH	7.8(42)E17	1.55%
CH ₄	3.3(3.0)E17	0.65%
OH	1.7(0.4)E16	0.03%

*Abundance as described in text for fit in Fig. 3C.

Colaprete, et al. (2010)

- ▶ Lunar volatiles are more than just water ice
- ▶ Characterizing composition and abundance is important to building ISRU systems
- ▶ Isotopic ratios of these molecules tell us about their origin, which can inform our understanding of key parameters like spatial distribution and texture

Capillary Absorption Spectrometer (CAS)



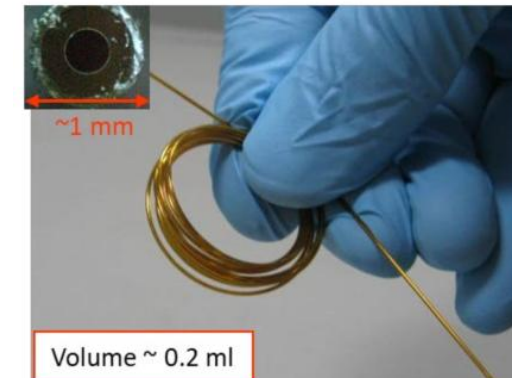
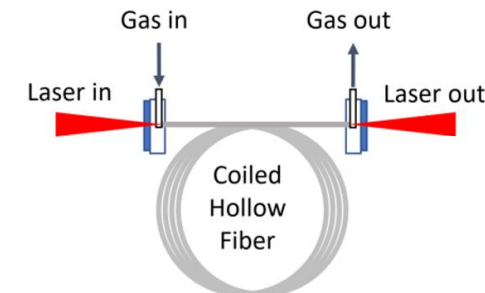
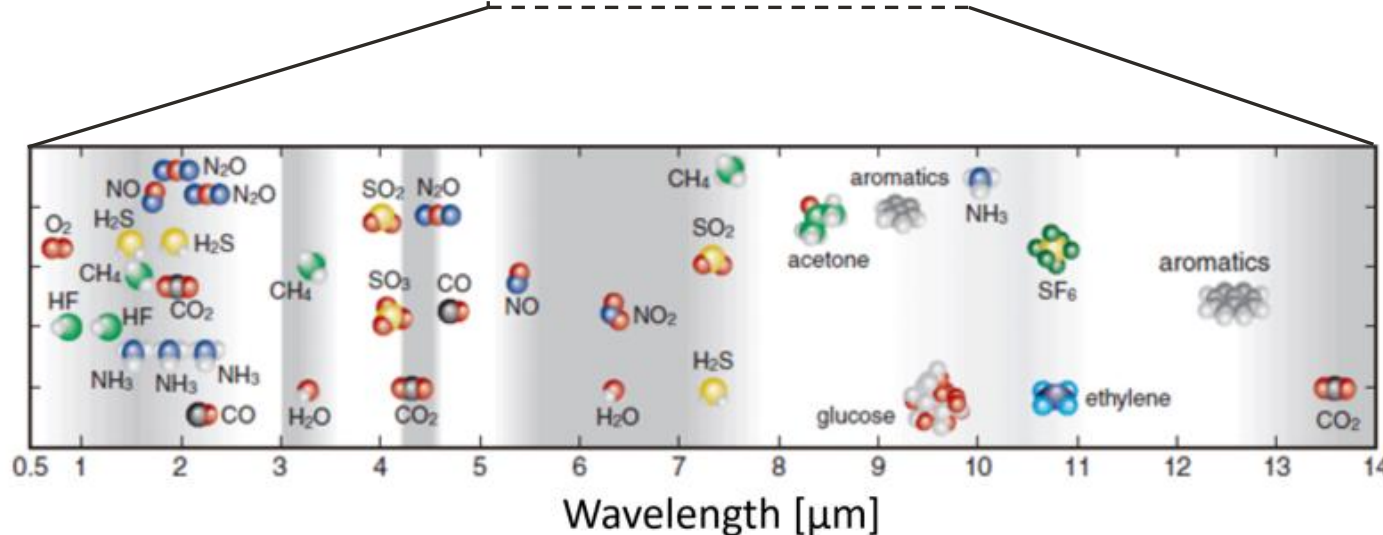
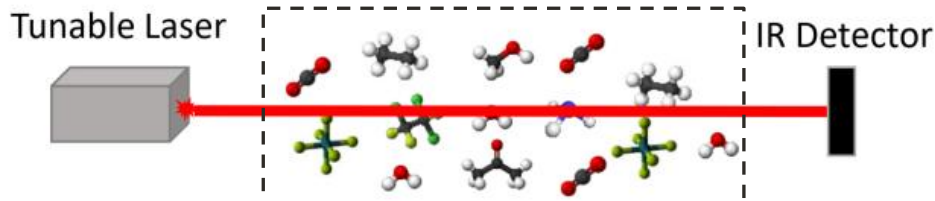
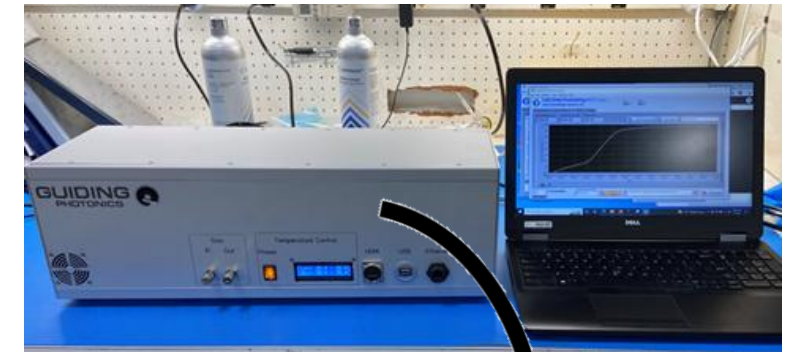
HONEYBEE ROBOTICS
A BLUE ORIGIN COMPANY

- ▶ Trace gas and isotope analyzer utilizing a low-volume (~1 mL) compact gas cell
- ▶ Mid-IR wavelength range enables unique identification of molecules, differentiating both species and isotopologues – e.g. differentiating HDO and H₂¹⁷O, both mass 19
- ▶ Identifies abundance of key volatiles of interest for the lunar surface – notably H₂O, H₂S, CO₂, SO₂ (and/or others depending on wavelengths selected)



OKSI

Intelligent. Adaptive. Integrated.



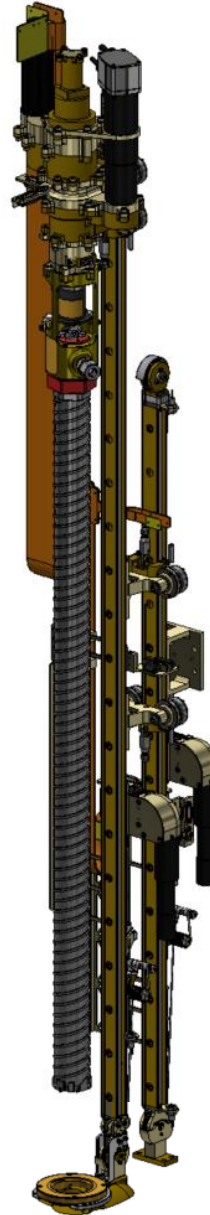
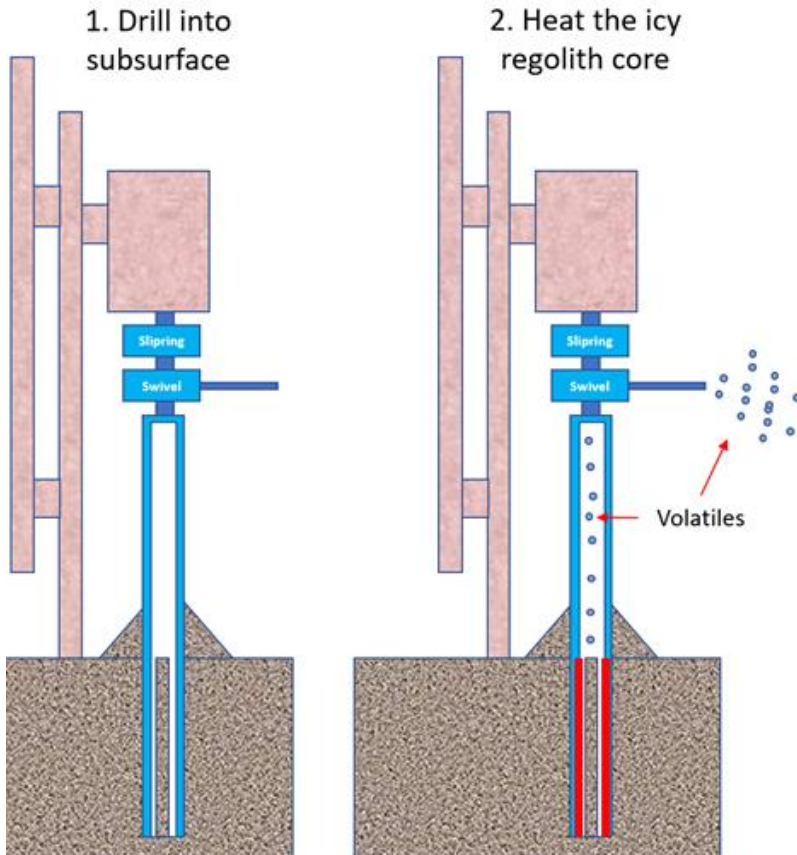
Kriesel, et al. (2023)

Planetary Volatiles Extractor (PVEx) Overview

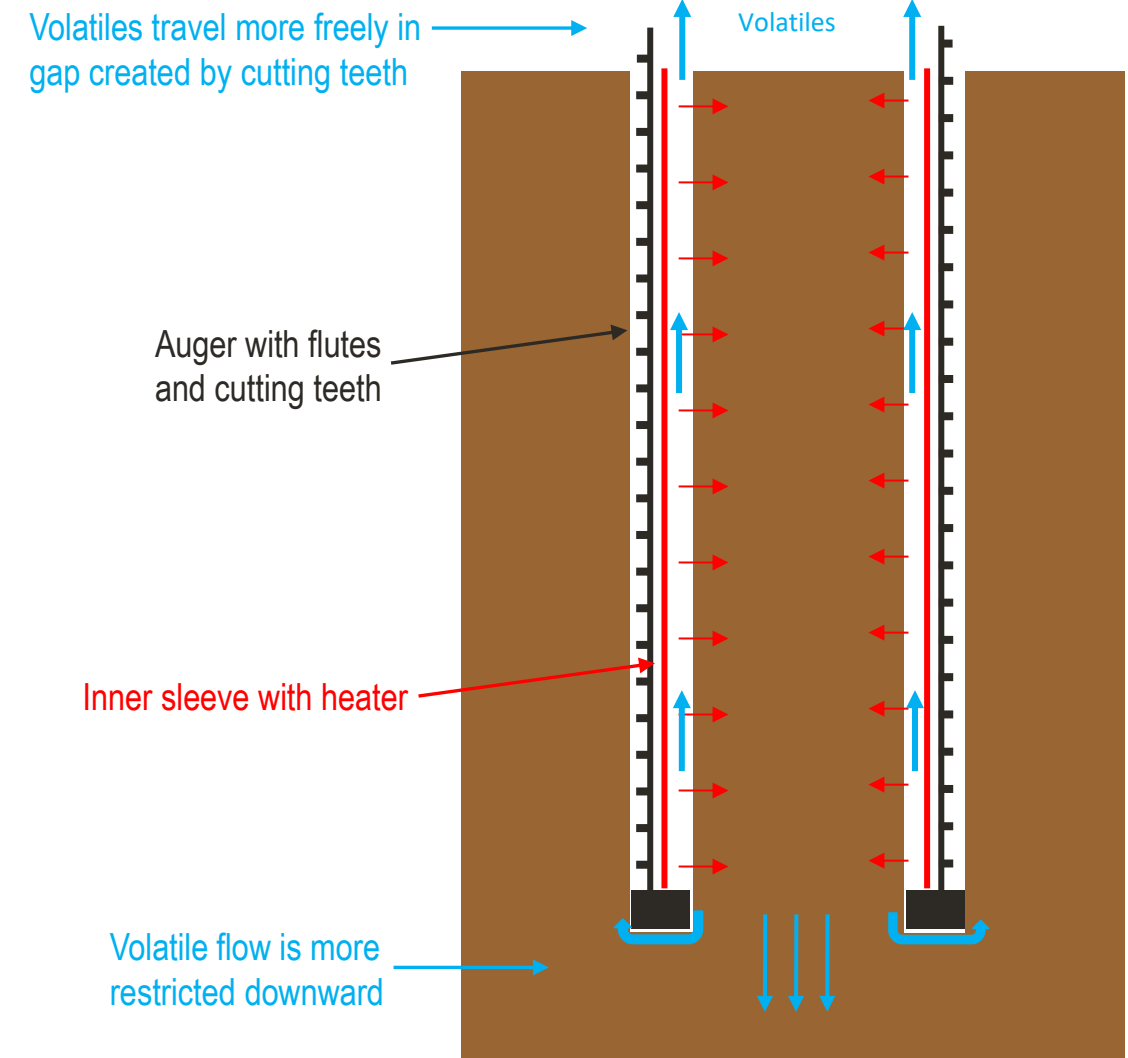


HONEYBEE ROBOTICS
A BLUE ORIGIN COMPANY

- ▶ 1-meter rotary percussive “coring” drill
- ▶ Auger contains a heater to volatilize ices in-situ
- ▶ Volatilized gas flows up through the drill string to a cold trap where it is collected



Volatile Extraction Concept



Lunar Capillary Absorption Spectrometer (LuCAS)



HONEYBEE ROBOTICS
A BLUE ORIGIN COMPANY



OKSI

Intelligent. Adaptive. Integrated.

+



Godard
SPACE FLIGHT CENTER

=

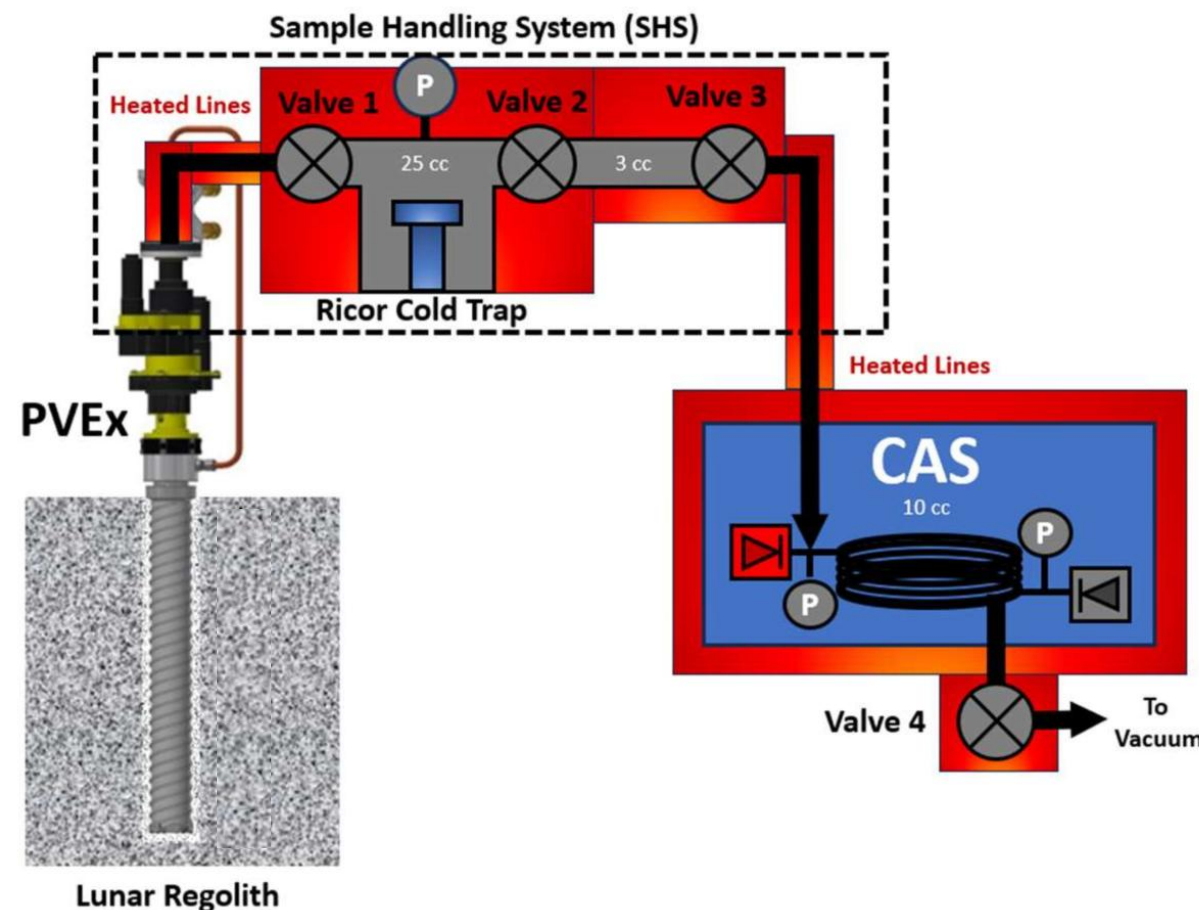
+



HONEYBEE ROBOTICS

A BLUE ORIGIN COMPANY

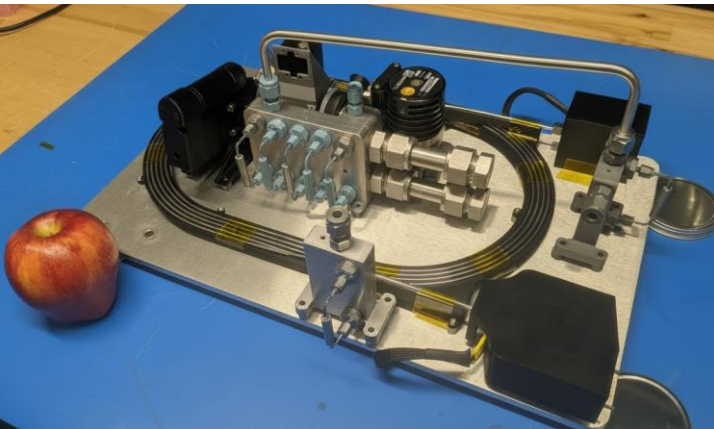
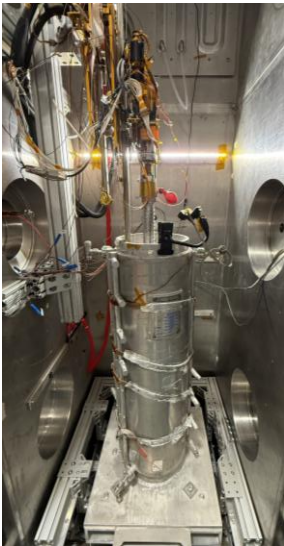
LuCAS is an end-to-end system for volatile extraction, collection, metering, and analysis on the lunar surface



LuCAS Development Timeline



SBIR Phase I



LuCAS DALI



SBIR Phase II



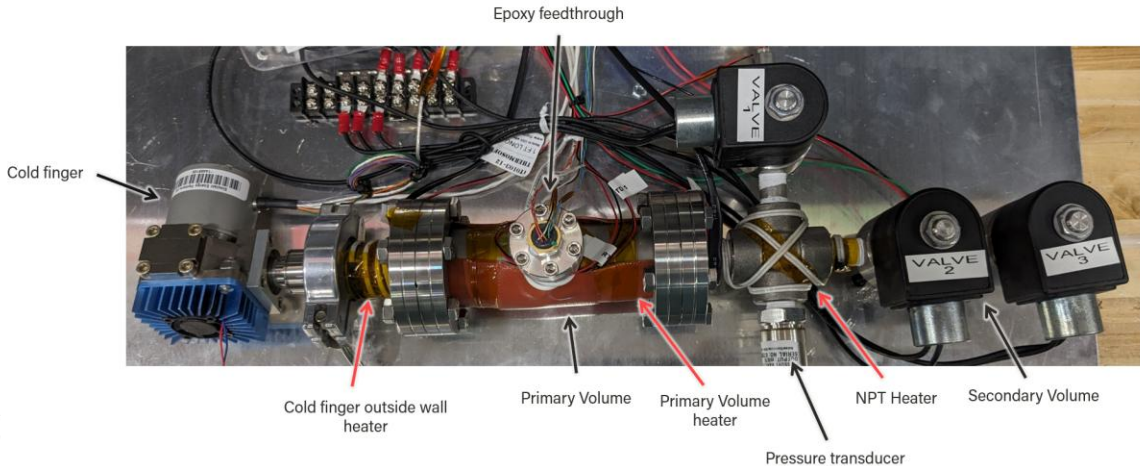
2.0" ID
0.5 m long



1.5" ID
1.0 m long



0.76" ID
1.0 m long



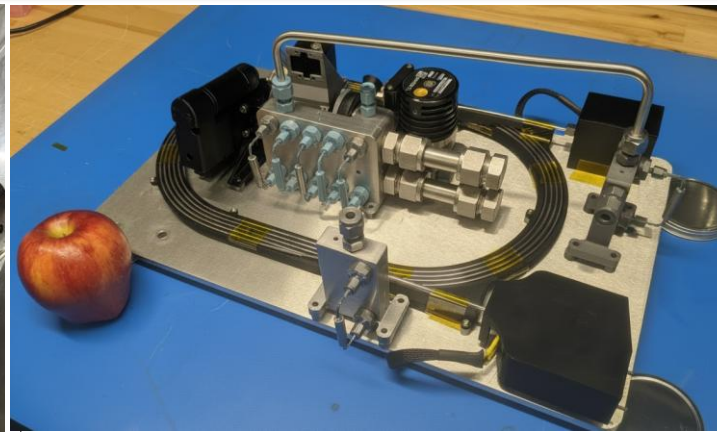
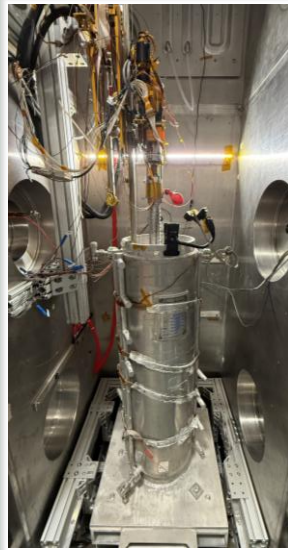
LuCAS Development Timeline



HONEYBEE ROBOTICS
A BLUE ORIGIN COMPANY



SBIR Phase I



LuCAS DALI

- ✓ TRL 5 Testing
- ✓ TRL 6 Design
- TRL 6 Qualification

2021

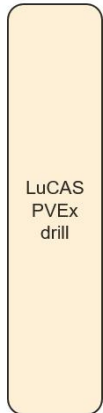
2022 – 2024

2024-2027

SBIR Phase II



2.0" ID
0.5 m long

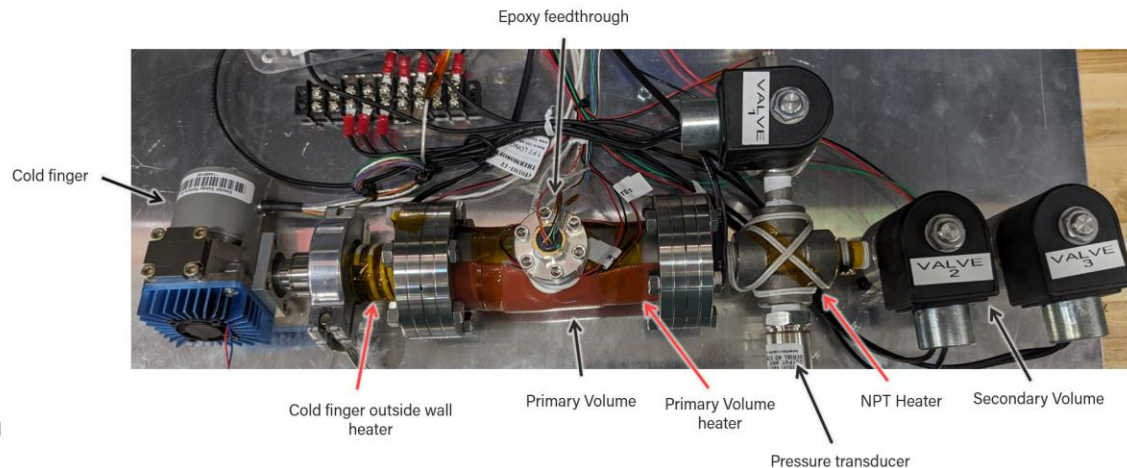


1.5" ID
1.0 m long



0.76" ID
1.0 m long

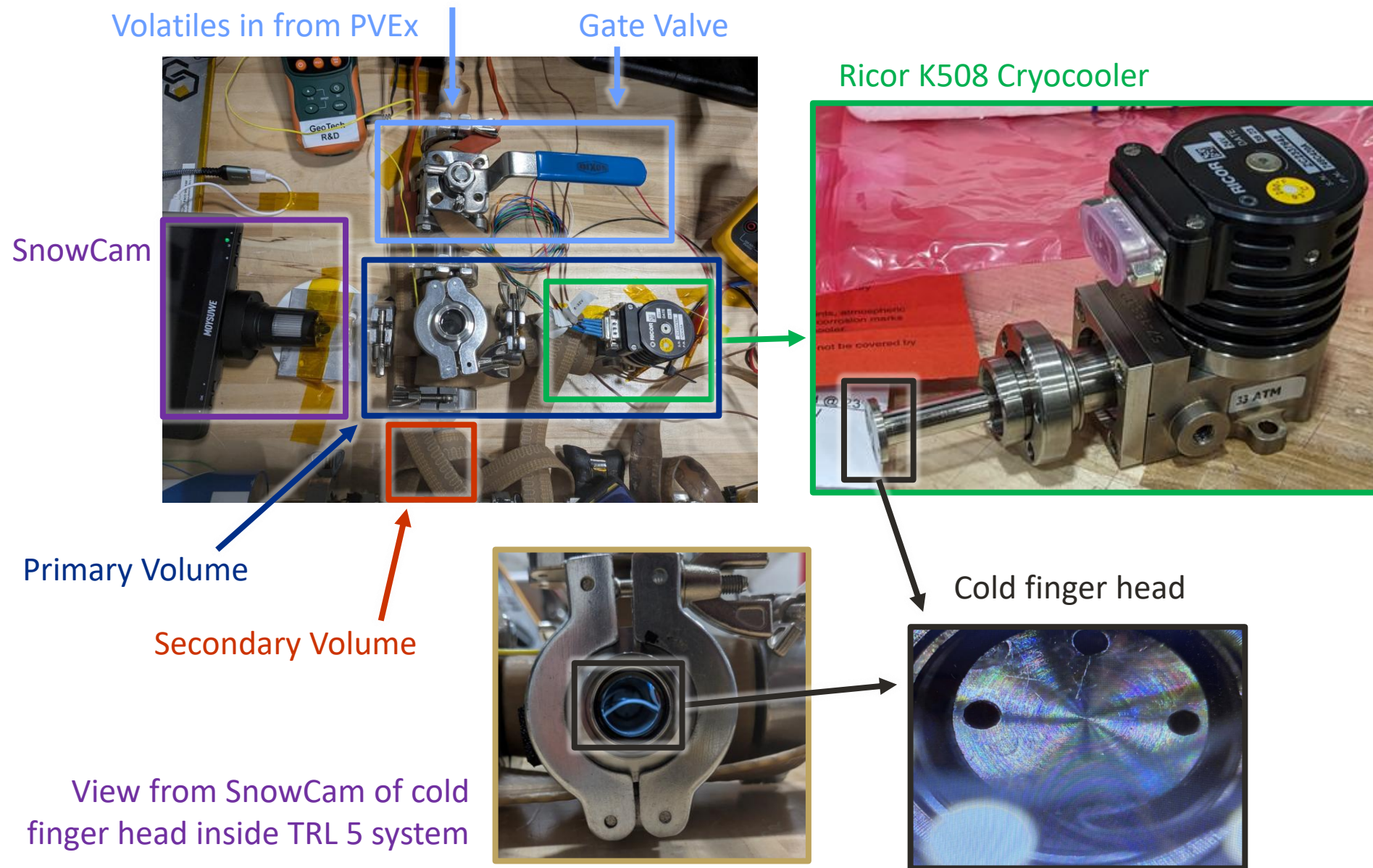
LuCAS
PVEEx
drill



TRL 5 Sample Handling System



HONEYBEE ROBOTICS
A BLUE ORIGIN COMPANY



Cold Trap Surface Area Study

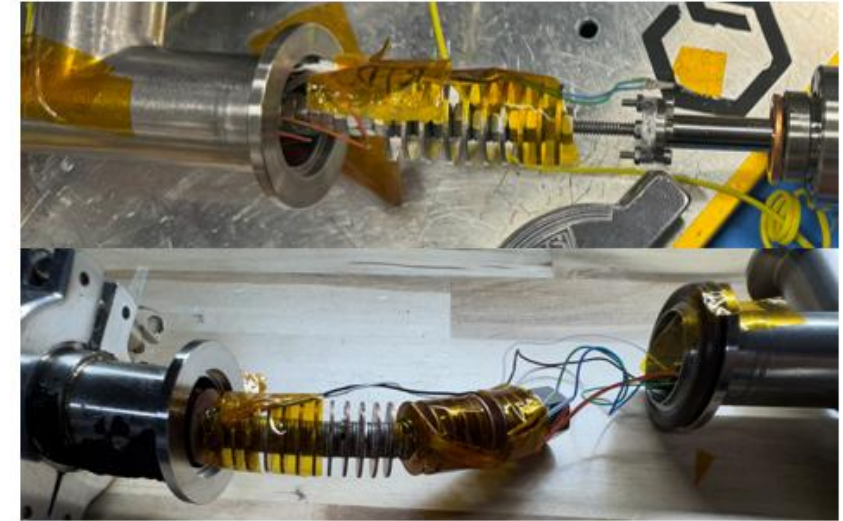


HONEYBEE ROBOTICS
A BLUE ORIGIN COMPANY

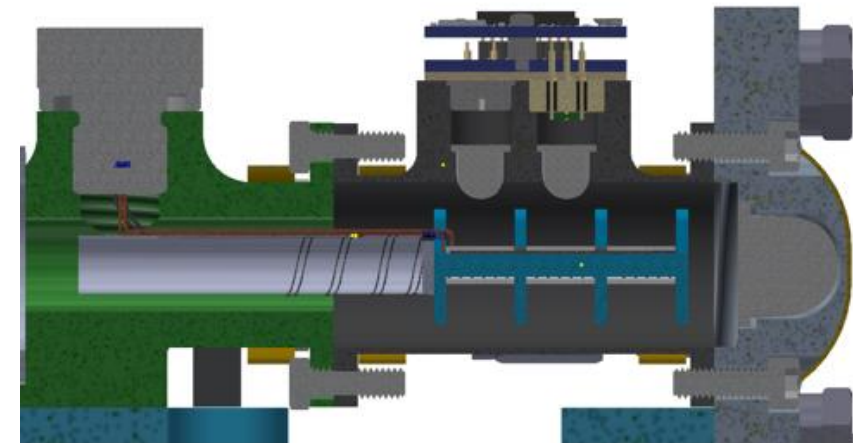
- ▶ To maximize volatile collection, the cold trap should (1) minimize surface temperature and (2) maximize surface area
- ▶ Bench top testing was performed to inform cold trap design and characterize minimum achievable temperature

Cold Trap Surface	Min. Temp Achieved
None – Cold Finger Only	-110 C
Extender (shown right)	-10 C

- ▶ Adding thermal mass to the cold trap dramatically reduced thermal performance, opted to proceed with TRL 5 testing with cold finger alone



TRL5 Cold Trap Designs



TRL6 SHS Conceptual Layout

Test Plan: Test Bed Overview



HONEYBEE ROBOTICS
A BLUE ORIGIN COMPANY

- ▶ Utilize TRIDENT/VIPER lunar TVAC testbed for PVEx + simulant
- ▶ TRL 5 sample handling and CAS subsystems connected via vapor transfer hose

TRIDENT/VIPER Testbed

Test Specs at a Glance

Simulant: LSP-2

Water Content: as low as possible

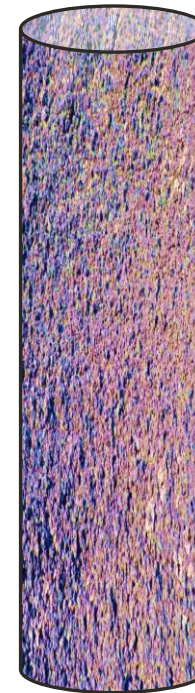
Pressure: $\leq 1\text{E-}2$ torr

Temperature: $\leq 200\text{K}$

Vapor transfer hose

TRL 5 SHS and SnowCam

TRL 5 CAS



Test Sample
1 m column of uniform
water ice distribution



Test Plan: Simulant Preparation



HONEYBEE ROBOTICS
A BLUE ORIGIN COMPANY

- ▶ Literature suggests as much as ~100 ppm adsorbed water can be found even at equatorial locations on the lunar surface

Article | [Open access](#) | Published: 22 September 2025

Lunar surface and subsurface water revealed by Chang'e-6

[Bin Liu](#), [Xingguo Zeng](#), [Rui Xu](#), [Shuai Li](#), [Jianjun Liu](#) , [Lin Guo](#), [Xin Ren](#), [Dawei Liu](#), [Wei Yan](#), [Wangli Chen](#), [Jinning Li](#), [Zhiping He](#) & [Chunlai Li](#) 

[Nature Astronomy](#) **9**, 1776–1784 (2025) | [Cite this article](#)

which are driven by the redistribution of fine regolith. The average water content of the exposed fine regolith of the shallow subsurface is ~76 ppm, which is lower than the surface abundance of ~105 ppm measured at the surface. The Chang'e-6 landing site also contains on

- ▶ Baked out regolith simulant in oven at 200C for ~4 hrs to get as dry as possible to inform end-to-end LuCAS limit of detection – **no water added for most tests**
 - ▶ Lowest achievable water content was 0.2 wt. %
 - ▶ In prior development work, lowest water content tests performed with PVEx were ~4 wt. %

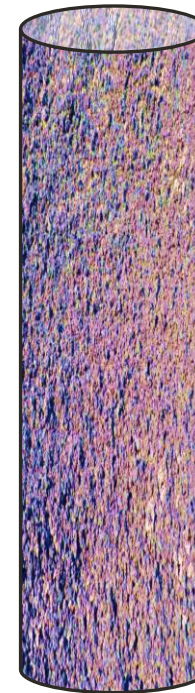
Test Specs at a Glance

Simulant: LSP-2

Water Content: From. 0.2-2 wt. %

Pressure: $\leq 1\text{E-}2$ torr

Temperature: $\leq 200\text{K}$



Test Sample
1 m column of uniform
water ice distribution

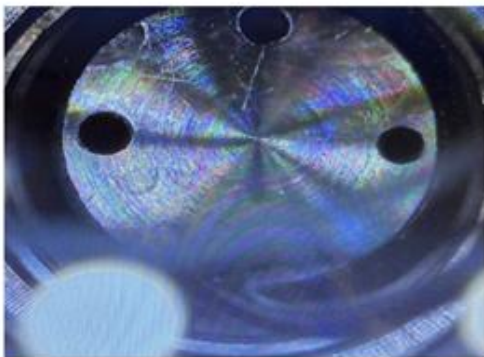


Volatile Accumulation Monitoring

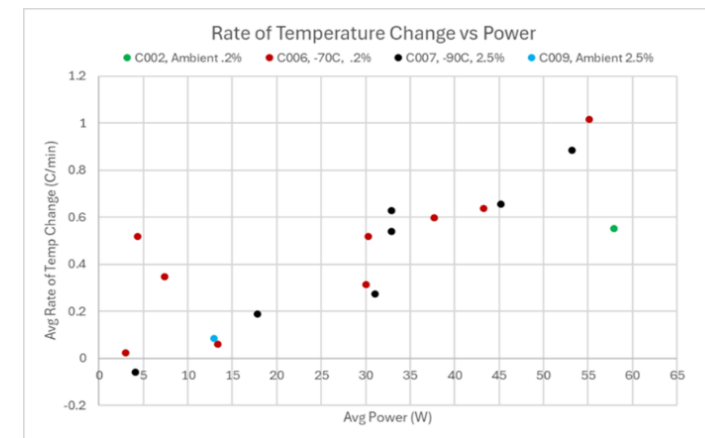


HONEYBEE ROBOTICS
A BLUE ORIGIN COMPANY

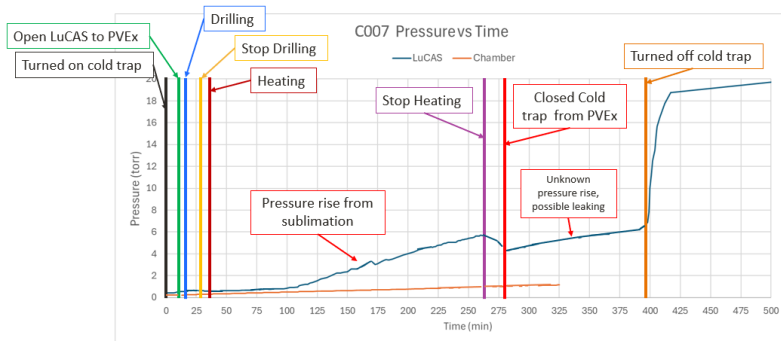
1 Image cold trap using SnowCam



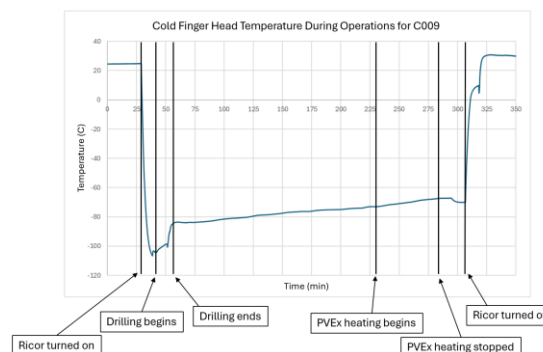
4 Observe PVEx rate of temp change



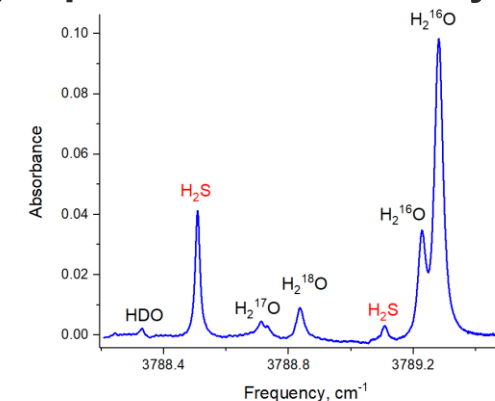
2 Monitor pressure in primary chamber



3 Monitor temp change of cold trap



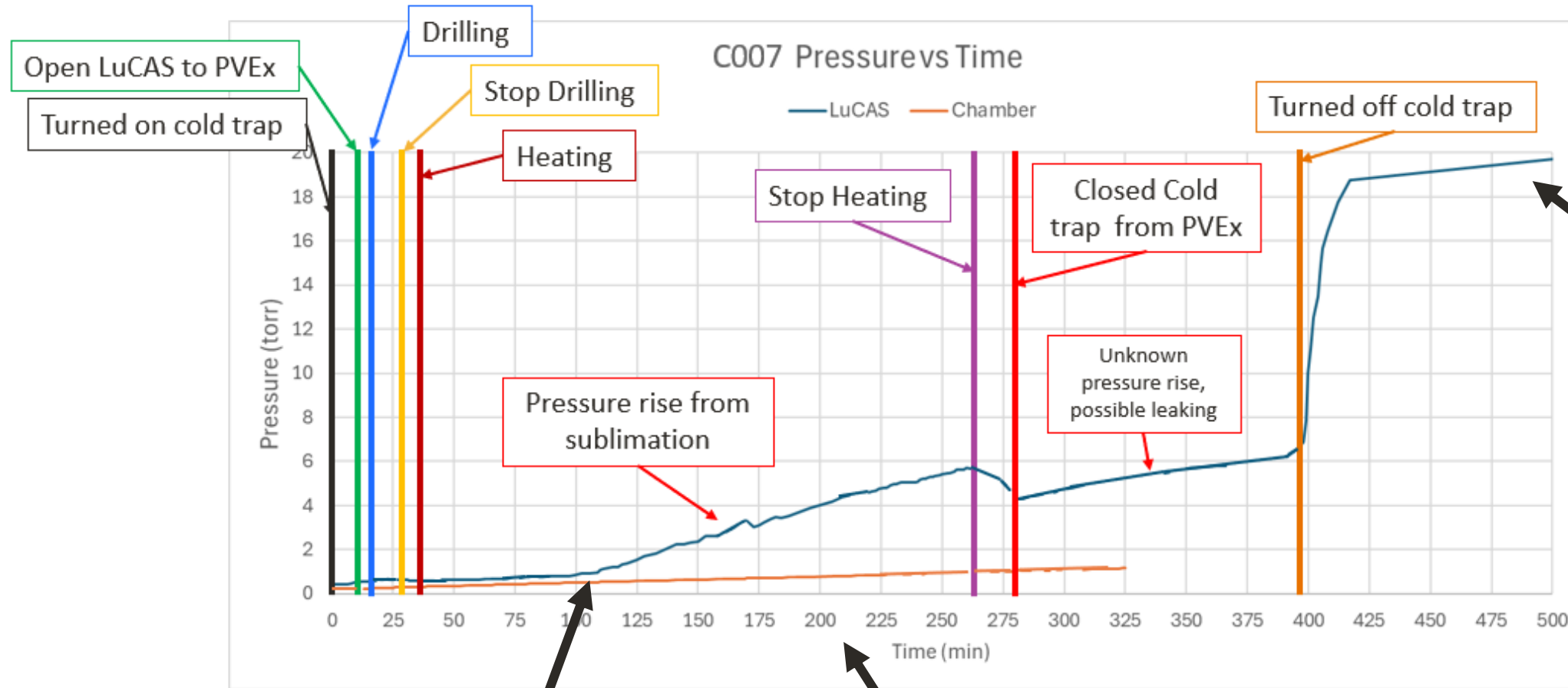
5 Open to CAS for analysis



Test Results: Primary Chamber Pressure



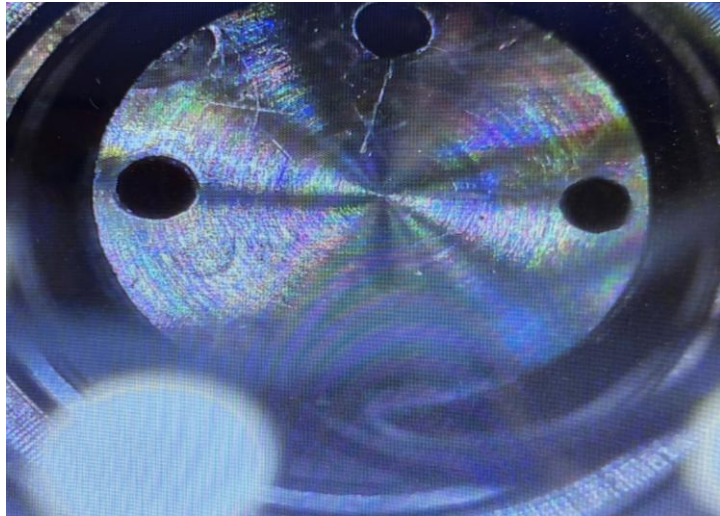
HONEYBEE ROBOTICS
A BLUE ORIGIN COMPANY



Takes time to begin phase change

Water accumulation over 4 hours

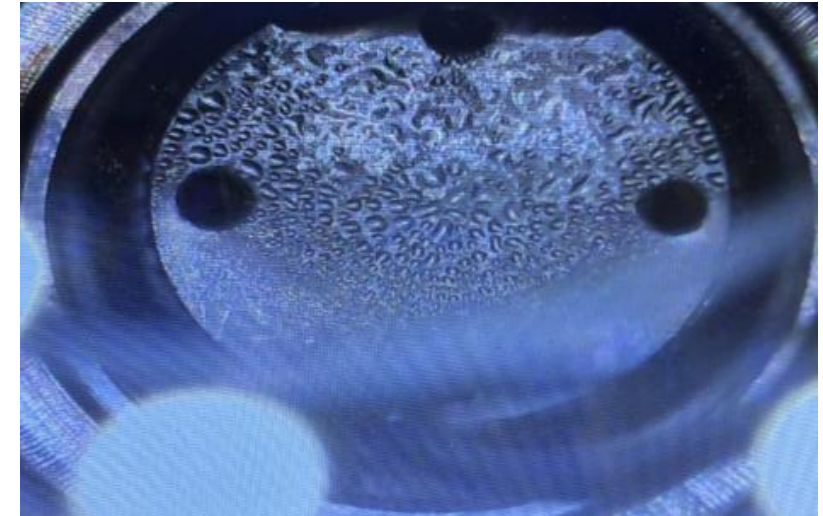
Test Results: SnowCam Images



Before Collection:
-110C cold trap



During Collection:
-70C cold trap



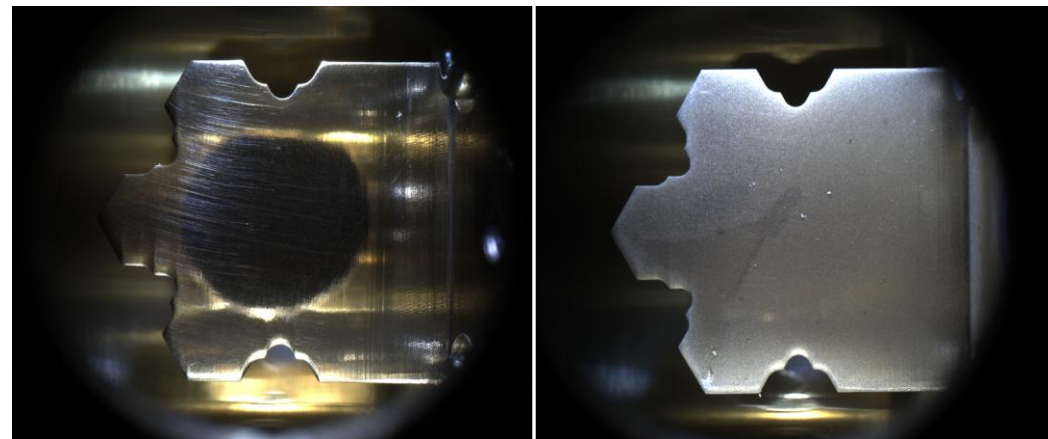
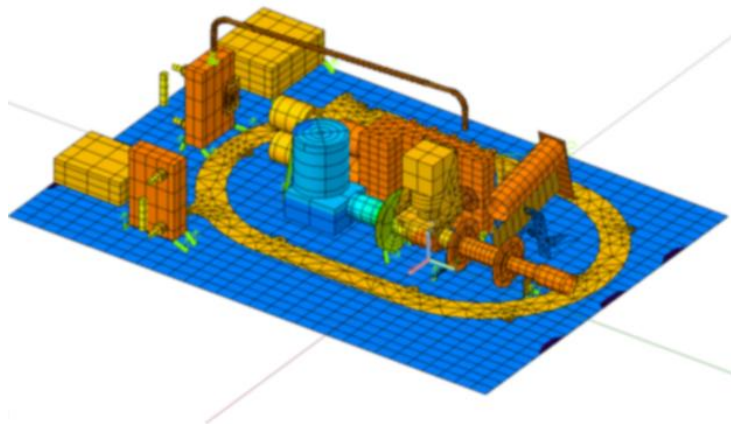
After Collection:
+22C cold trap

Lessons Learned for TRL 6 Design



HONEYBEE ROBOTICS
A BLUE ORIGIN COMPANY

- ▶ **Thermal design is crucial to the success of LuCAS**
 - ▶ Reduce parasitic loads to the cold trap to maximize power efficiency (e.g. spend available power to get as cold as possible)
 - ▶ Most interior surface area must be kept hot to avoid isotopic fractionation of the sample
 - ▶ Laser assembly has tight operational temperature and stability requirements
 - ▶ Cryocooler must be able to efficiently reject heat for best performance
- ▶ Can successfully use multiple data sources, including opportunistic measurements, to inform volatile extraction status. Tests also informed anticipated duration of each step, which matures power and energy consumption estimates
- ▶ SnowCam images provide valuable context - changes can be subtle and we don't know what to expect on the Moon!

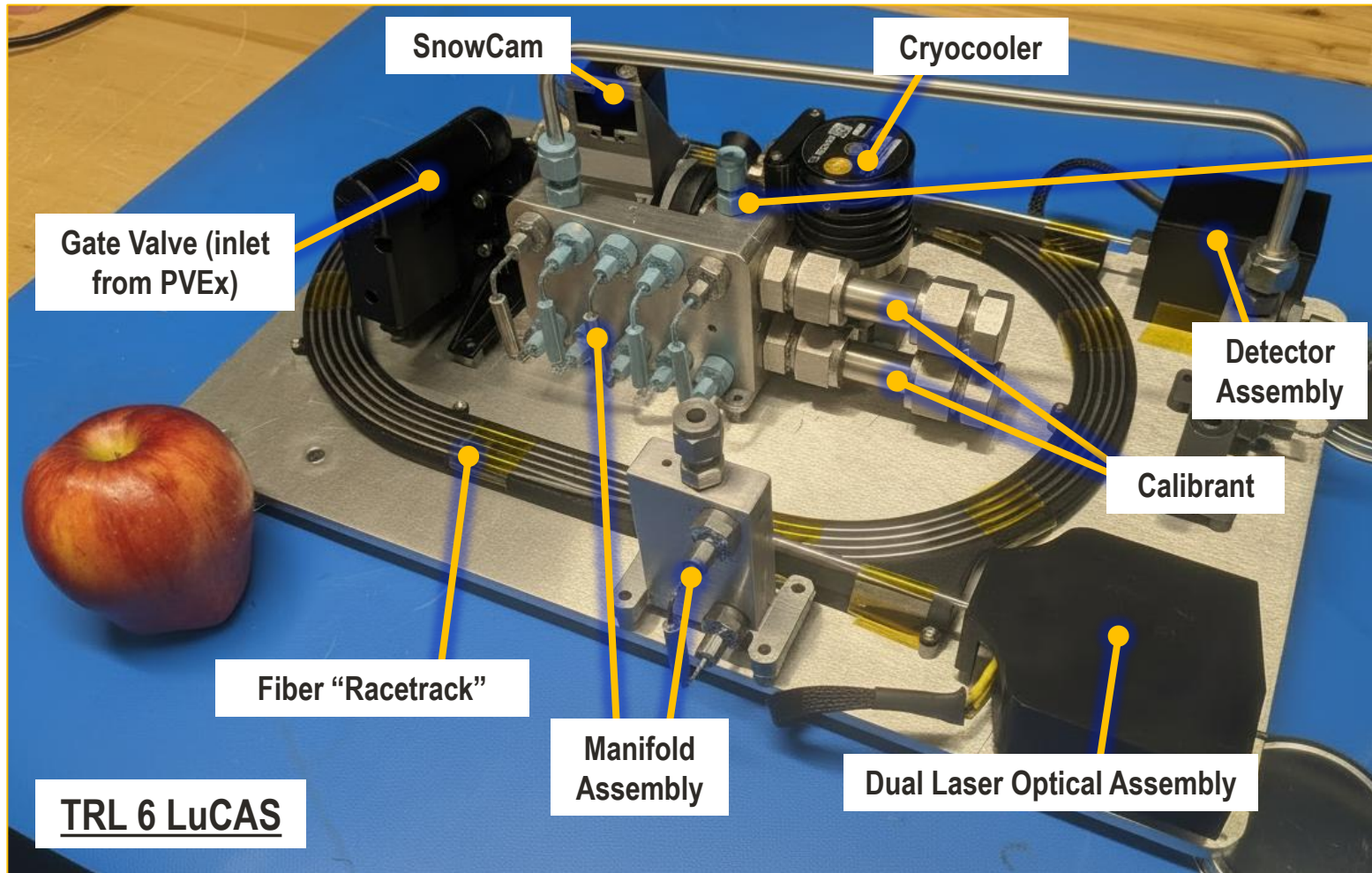


Ongoing Work – TRL 6 Development



HONEYBEE ROBOTICS
A BLUE ORIGIN COMPANY

- ▶ Lessons learned from TRL 5 testing informed TRL 6 hardware design, CDR held in January
- ▶ TRL 6 hardware build is ongoing, end-to-end TVAC tests, thermal stress tests, and vibe test campaign taking place this summer



Cold finger extender designs





HONEYBEE ROBOTICS

A BLUE ORIGIN COMPANY